Example: Minimum Cost Flow Problem

Given: directed graph D = (V, A), with arc capacities $u : A \to \mathbb{R}_{\geq 0}$, arc costs $c : A \to \mathbb{R}$, and node balances $b : V \to \mathbb{R}$.

Interpretation:

- ▶ nodes v ∈ V with b(v) > 0 (b(v) < 0) have supply (demand) and are called sources (sinks)</p>
- the capacity u(a) of arc a ∈ A limits the amount of flow that can be sent through arc a.

Task: find a *flow* $x : A \to \mathbb{R}_{\geq 0}$ obeying capacities and satisfying all supplies and demands, that is,

$$0 \le x(a) \le u(a) \qquad \qquad \text{for all } a \in A,$$

$$\sum_{a \in \delta^+(v)} x(a) - \sum_{a \in \delta^-(v)} x(a) = b(v) \qquad \qquad \text{for all } v \in V,$$

such that x has minimum cost $c(x) := \sum_{a \in A} c(a) \cdot x(a)$.



Example: Minimum Cost Flow Problem (cont.)

Formulation as a linear program (LP):

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minimize
$$\sum_{a \in A} c(a) \cdot x(a)$$
 (1.1)
subject to $\sum_{a \in \delta^+(v)} x(a) - \sum_{a \in \delta^-(v)} x(a) = b(v)$ for all $v \in V$, (1.2)

$$x(a) \le u(a)$$
for all $a \in A$,(1.3) $x(a) \ge 0$ for all $a \in A$.(1.4)

▶ Objective function given by (1.1). Set of feasible solutions:

$$X = \{x \in \mathbb{R}^A \mid x \text{ satisfies (1.2), (1.3), and (1.4)}\}$$

Example: Minimum Cost Flow Problem (cont.)

Formulation as a linear program (LP):

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Notice that (1.1) is a linear function of x and (1.2) – (1.4) are linear equations and linear inequalities, respectively. → linear program

Fixed costs $w : A \to \mathbb{R}_{\geq 0}$.

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This leads to the following mixed-integer linear program (MIP):

$$\begin{array}{ll} \text{minimize} & \sum_{a \in A} c(a) \cdot x(a) + \sum_{a \in A} w(a) \cdot y(a) \\ \text{subject to} & \sum_{a \in \delta^+(v)} x(a) - \sum_{a \in \delta^-(v)} x(a) = b(v) & \text{for all } v \in V, \\ & x(a) \leq u(a) \cdot y(a) & \text{for all } a \in A, \\ & x(a) \geq 0 & \text{for all } a \in A. \\ & y(a) \in \{0, 1\} & \text{for all } a \in A. \end{array}$$

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MIP: Linear program where some variables may only take integer values.

Given: undirected graph G = (V, E), weight function $w : E \to \mathbb{R}$.

Task: find matching $M \subseteq E$ with maximum total weight.

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Example: Traveling Salesperson Problem (TSP)

Given: complete graph K_n on n nodes, weight function $w : E(K_n) \to \mathbb{R}$.

Task: find a Hamiltonian circuit with minimum total weight.

(A Hamiltonian circuit visits every node exactly once.)

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Formulation as an integer linear program? (maybe later!)

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$$\begin{array}{ll} \text{minimize} & \sum_{v \in V} w(v) \cdot x_v \\ \text{subject to} & x_v + x_{v'} \ge 1 \\ & x_v \in \{0, 1\} \end{array} & \quad \text{for all } e = \{v, v'\} \in E, \\ & \text{for all } v \in V. \end{array}$$

Markowitz' Portfolio Optimisation Problem

Given: *n* different securities (stocks, bonds, etc.) with random returns, target return *R*, for each security $i \in [n]$:

• expected return μ_i , variance σ_i

For each pair of securities i, j:

• covariance ρ_{ij} ,

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$$\begin{array}{ll} \text{minimize} & \sum_{i,j} \rho_{ij}\sigma_i\sigma_j x_i x_j \\ \text{subject to} & \sum_i x_i = 1 \\ & \sum_i \mu_i x_i \geq R \\ & x_i \geq 0, \end{array}$$
 for all i .

For a given optimization problem:

► How to find an optimal solution?

- ► How to find an optimal solution?
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- Does there exist an efficient algorithm with "small" worst-case running time?
- How to formulate the problem as a (mixed integer) linear program?
- Is there a useful special structure of the problem?

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Chapter 2: Linear Programming Basics

(Bertsimas & Tsitsiklis, Chapter 1)

Example of a Linear Program

minimize
$$2x_1 - x_2 + 4x_3$$

subject to $x_1 + x_2 + x_4 \leq 2$ constraining
 $3x_2 - x_3 = 5$
 $x_3 + x_4 \geq 3$
 $x_1 \geq 0$
 $x_3 \leq 0$

Example of a Linear Program

Remarks.

- objective function is linear in vector of variables $x = (x_1, x_2, x_3, x_4)^T$
- constraints are linear inequalities and linear equations
- last two constraints are special (non-negativity and non-positivity constraint, respectively)

minimize	$c^T \cdot x = C, x$	x, + C2 X2 + + Cn Xn	
subject to	$a_i^T \cdot x \ge b_i$	for $i \in M_1$,	(2.1)
	$a_i^T \cdot x = b_i$	for $i \in M_2$,	(2.2)
	$a_i^T \cdot x \leq b_i$	for $i \in M_3$,	(2.3)
	$x_j \ge 0$	for $j\in \mathit{N}_1$,	(2.4)
	$x_j \leq 0$	for $j\in \mathit{N}_2$,	(2.5)

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with $c \in \mathbb{R}^n$, $a_i \in \mathbb{R}^n$ and $b_i \in \mathbb{R}$ for $i \in M_1 \cup M_2 \cup M_3$ (finite index sets), and $N_1, N_2 \subseteq \{1, \ldots, n\}$ given.

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▶ $x \in \mathbb{R}^n$ satisfying constraints (2.1) – (2.5) is a feasible solution.

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 $c^T \cdot x^* \leq c^T \cdot x$ for all feasible solutions x.

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▶ linear program is unbounded if, for all $k \in \mathbb{R}$, there is a feasible solution $x \in \mathbb{R}^n$ with $c^T \cdot x \leq k$.