## Example: Minimum Cost Flow Problem

Given: directed graph $D=(V, A)$, with arc capacities $u: A \rightarrow \mathbb{R}_{\geq 0}$,
arc costs $c: A \rightarrow \mathbb{R}$, and node balances $b: V \rightarrow \mathbb{R}$.

## Interpretation:

- nodes $v \in V$ with $b(v)>0(b(v)<0)$ have supply (demand) and are called sources (sinks)
- the capacity $u(a)$ of arc $a \in A$ limits the amount of flow that can be sent through arc $a$.

Task: find a flow $x$ : $A \rightarrow \mathbb{R}_{\geq 0}$ obeying capacities and satisfying all supplies and demands, that is,

$$
\begin{array}{cl}
0 \leq x(a) \leq u(a) & \text { for all } a \in A, \\
\sum_{a \in \delta^{+}(v)} x(a)-\sum_{a \in \delta^{-}(v)} x(a)=b(v) & \text { for all } v \in V, \\
\text { such that } x \text { has minimum } \operatorname{cost} c(x):=\sum_{a \in A} c(a) \cdot x(a) . & \delta^{-(v)} \delta^{+}(v)
\end{array}
$$

Example: Minimum Cost Flow Problem (cont.)
Formulation as a linear program (LP):


## Example: Minimum Cost Flow Problem (cont.)

Formulation as a linear program (LP):

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& x(a) \leq u(a) & \\
& x(a) \geq 0 & \text { for all } a \in A  \tag{1.4}\\
& \text { for all } a \in A
\end{array}
$$

- Objective function given by (1.1). Set of feasible solutions:

$$
X=\left\{x \in \mathbb{R}^{A} \mid x \text { satisfies }(1.2),(1.3), \text { and }(1.4)\right\}
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## Example: Minimum Cost Flow Problem (cont.)

Formulation as a linear program (LP):

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- Notice that (1.1) is a linear function of $x$ and (1.2) - (1.4) are linear equations and linear inequalities, respectively. $\longrightarrow$ linear program

Example (cont.): Adding Fixed Cost
Fixed costs $w: A \rightarrow \mathbb{R}_{\geq 0}$.
If arc $a \in A$ shall be used (i. e., $x(a)>0$ ), it must be bought at cost $w(a)$.

## Example (cont.): Adding Fixed Cost

Fixed costs $w: A \rightarrow \mathbb{R}_{\geq 0}$.
If arc $a \in A$ shall be used (i. e., $x(a)>0$ ), it must be bought at cost $w(a)$. Add variables $y(a) \in\{0,1\}$ with $y(a)=1$ if arc $a$ is used, 0 otherwise.

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This leads to the following mixed-integer linear program (MIP):

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\begin{array}{lll}
\text { minimize } & \sum_{a \in A} c(a) \cdot x(a)+\sum_{a \in A} w(a) \cdot y(a) & \\
\text { subject to } & \sum_{a \in \delta^{+}(v)} x(a)-\sum_{a \in \delta^{-}(v)} x(a)=b(v) & \text { for all } v \in V \\
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MIP: Linear program where some variables may only take integer values.

Example: Maximum Weighted Matching Problem
Given: undirected graph $G=(V, E)$, weight function $w: E \rightarrow \mathbb{R}$.
Task: find matching $M \subseteq E$ with maximum total weight.
( $M \subseteq E$ is a matching if every node is incident to at most one edge in $M$.)


Application:
Task as signmend


Staff

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Variables: $x_{e} \in\{0,1\}$ for $e \in E$ with $x_{e}=1$ if and only if $e \in M$.

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$$
\begin{array}{rll}
\operatorname{maximize} & \sum_{e \in E} w(e) \cdot x_{e} & \\
\text { subject to } & \sum_{e \in \delta(v)} x_{e} \leq 1 & \text { for all } v \in V \\
& x_{e} \in\{0,1\} & \text { for all } e \in E
\end{array}
$$

IP: Linear program where all variables may only take integer values.

## Example: Traveling Salesperson Problem (TSP)

Given: complete graph $K_{n}$ on $n$ nodes, weight function $w: E\left(K_{n}\right) \rightarrow \mathbb{R}$.
Task: find a Hamiltonian circuit with minimum total weight.
(A Hamiltonian circuit visits every node exactly once.)

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Formulation as an integer linear program? (maybe later!)

## Example: Weighted Vertex Cover Problem

Given: undirected graph $G=(V, E)$, weight function $w: V \rightarrow \mathbb{R}_{\geq 0}$.
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$$
\begin{array}{rll}
\operatorname{minimize} & \sum_{v \in V} w(v) \cdot x_{v} & \\
\text { subject to } & x_{v}+x_{v^{\prime}} \geq 1 & \text { for all } e=\left\{v, v^{\prime}\right\} \in E \\
& x_{v} \in\{0,1\} & \text { for all } v \in V .
\end{array}
$$

## Markowitz' Portfolio Optimisation Problem

Given: $n$ different securities (stocks, bonds, etc.) with random returns, target return $R$, for each security $i \in[n]$ :

- expected return $\mu_{i}$, variance $\sigma_{i}$

For each pair of securities $i, j$ :

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Formulation as a quadratic programme (QP):

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Formulation as a quadratic programme (QP):

$$
\begin{array}{rlr}
\operatorname{minimize} & \sum_{i, j} \rho_{i j} \sigma_{i} \sigma_{j} x_{i} x_{j} & \\
\text { subject to } & \sum_{i} x_{i}=1 \\
& \sum_{i} \mu_{i} x_{i} \geq R & \\
& x_{i} \geq 0, & \text { for all } i .
\end{array}
$$

## Typical Questions

For a given optimization problem:

- How to find an optimal solution?


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- How to formulate the problem as a (mixed integer) linear program?


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- How to find an optimal solution?
- How to find a feasible solution?
- Does there exist an optimal/feasible solution?
- How to prove that a computed solution is optimal?
- How difficult is the problem?
- Does there exist an efficient algorithm with "small" worst-case running time?
- How to formulate the problem as a (mixed integer) linear program?
- Is there a useful special structure of the problem?


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# Chapter 2: Linear Programming Basics 

(Bertsimas \& Tsitsiklis, Chapter 1)

Example of a Linear Program

$$
\begin{aligned}
& \text { minimize } 2 x_{1}-x_{2}+4 x_{3} \text { objectico fincfion } \\
& \text { subject to } x_{1}+x_{2} \quad+x_{4} \leq 2 \text { comstuainfy } \\
& x_{1}
\end{aligned}
$$

## Example of a Linear Program

$$
\begin{aligned}
& \text { minimize } 2 x_{1}-x_{2}+4 x_{3} \\
& \text { subject to } x_{1}+x_{2}+x_{4} \leq 2 \\
& 3 x_{2}-x_{3}=5 \\
& x_{3}+x_{4} \geq 3 \\
& x_{1} \\
& \geq 0 \\
& x_{3} \quad \leq 0
\end{aligned}
$$

## Remarks.

- objective function is linear in vector of variables $x=\left(x_{1}, x_{2}, x_{3}, x_{4}\right)^{T}$
- constraints are linear inequalities and linear equations
- last two constraints are special (non-negativity and non-positivity constraint, respectively)


## General Linear Program

$$
\begin{array}{rcc}
\operatorname{minimize} & c^{T} \cdot x=c_{1} x_{1}+C_{2} x_{2}-1 \ldots+C_{n} x_{n} \\
\text { subject to } & a_{i}^{T} \cdot x \geq b_{i} & \text { for } i \in M_{1}, \\
& a_{i}^{T} \cdot x=b_{i} & \text { for } i \in M_{2}, \\
& a_{i}^{T} \cdot x \leq b_{i} & \text { for } i \in M_{3}, \\
& x_{j} \geq 0 & \text { for } j \in N_{1}, \\
& x_{j} \leq 0 & \text { for } j \in N_{2}, \tag{2.5}
\end{array}
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x_{j} \geq 0 & \text { for } j \in N_{1}, \\
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\end{array}
$$

with $c \in \mathbb{R}^{n}, a_{i} \in \mathbb{R}^{n}$ and $b_{i} \in \mathbb{R}$ for $i \in M_{1} \dot{\cup} M_{2} \dot{\cup} M_{3}$ (finite index sets), and $N_{1}, N_{2} \subseteq\{1, \ldots, n\}$ given.

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- $x \in \mathbb{R}^{n}$ satisfying constraints (2.1) - (2.5) is a feasible solution.


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$$

- linear program is unbounded if, for all $k \in \mathbb{R}$, there is a feasible solution $x \in \mathbb{R}^{n}$ with $c^{T} \cdot x \leq k$.

