

Example:

Basis 3 / those were swapped.

$$B = \left(\begin{array}{cccc|cccc} 1 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 3 & 0 & 1 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \quad \text{I - II - III}$$

$$\left(\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 3 & 0 & 1 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \quad \text{IV - 3I - III}$$

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$$B^{-1}$$

$$x_B = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$$

$$B^{-1} \cdot b = \begin{pmatrix} 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -3 & 3 & 2 & 1 \end{pmatrix} \begin{pmatrix} 4 \\ 2 \\ 3 \\ 6 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \\ 3 \\ 6 \end{pmatrix} = \begin{pmatrix} x_2 \\ x_1 \\ x_3 \\ x_4 \end{pmatrix}$$

Basic Columns and Basic Solutions

Observation 2.15.

Let $x \in \mathbb{R}^n$ be a basic solution, then:

- ▶ $B \cdot x_B = b$ and thus $x_B = B^{-1} \cdot b$;
- ▶ x is a **basic feasible solution** if and only if $x_B = B^{-1} \cdot b \geq 0$.

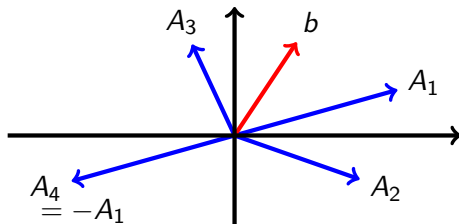
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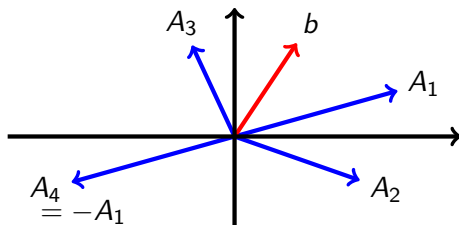
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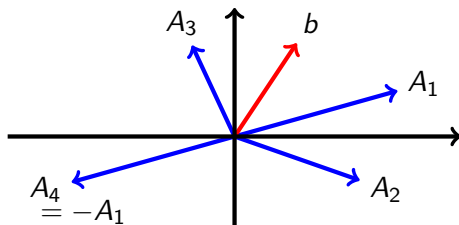
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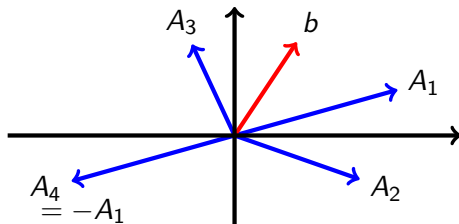
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- ▶ A_1, A_3 or A_2, A_3 form bases with corresp. basic feasible solutions.
- ▶ A_1, A_4 do not form a basis.
- ▶ A_1, A_2 and A_2, A_4 and A_3, A_4 form bases with infeasible basic solution.

Bases and Basic Solutions

Corollary 2.16.

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- ▶ Thus, different basic solutions correspond to different bases.
- ▶ **But:** two different bases might yield the same basic solution.

Example: If $b = 0$, then $x = 0$ is the only basic solution.

Adjacent Bases

Definition 2.17.

Two bases $A_{B(1)}, \dots, A_{B(m)}$ and $A_{B'(1)}, \dots, A_{B'(m)}$ are **adjacent** if they share all but one column.

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Observation 2.18.

- a** Two adjacent basic solutions can always be obtained from two adjacent bases.
- b** If two adjacent bases lead to distinct basic solutions, then the latter are adjacent.

Degeneracy

Definition 2.19.

A basic solution x of a polyhedron P is **degenerate** if more than n constraints are active at x .

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A basic solution x of a polyhedron P is **degenerate** if more than n constraints are active at x .

Observation 2.20.

Let $P = \{x \in \mathbb{R}^n \mid A \cdot x = b, x \geq 0\}$ be a polyhedron in standard form with $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^m$.

- a** A basic solution $x \in P$ is **degenerate** if and only if more than $n - m$ components of x are zero.
- b** For a **non-degenerate** basic solution $x \in P$, there is a unique basis.

Three Different Reasons for Degeneracy

i redundant variables

Example:

$$x_1 + x_2 = 1$$

$$x_3 = 0$$

$$x_1, x_2, x_3 \geq 0$$

$$\longleftrightarrow A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Three Different Reasons for Degeneracy

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Example:

$$\begin{array}{rcl} x_1 + x_2 & = & 1 \\ & x_3 & = 0 \\ x_1, x_2, x_3 & \geq & 0 \end{array} \longleftrightarrow A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

ii redundant constraints

Example:

$$\begin{array}{rcl} x_1 + 2x_2 & \leq & 3 \\ 2x_1 + x_2 & \leq & 3 \\ x_1 + x_2 & \leq & 2 \\ x_1, x_2 & \geq & 0 \end{array} \Rightarrow 3x_1 + 3x_2 \leq 6$$

redundant,
implied by
other constraints

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iii geometric reasons

Example: Octahedron

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Example: Octahedron

Observation 2.21.

Perturbing the right hand side vector b may remove degeneracy.