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\min & & c^{T} \cdot x & \\
\text { s.t. } & x(\gamma(S)) & \leq|S|-1 & \\
x(E) & =|V|-1 & &  \tag{6.2}\\
& & & \\
& & \in\{0,1\} &
\end{array}\right) \text { for all } \emptyset \neq S \subset V
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- $F$ does not contain circuit due to (6.1) and $n-1$ edges due to (6.2).
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Observations:

- Feasible solution $x \in\{0,1\}^{E}$ is characteristic vector of subset $F \subseteq E$.
- $F$ does not contain circuit due to (6.1) and $n-1$ edges due to (6.2).
- Thus, $F$ forms a spanning tree of $G$.
- Moreover, the edge set of an arbitrary spanning tree of $G$ yields a feasible solution $x \in\{0,1\}^{E}$.

Discrete Problems as geometric problems:
Graph $a$ : Spanning trees of $a$ as characteristic vectors

$$
a_{0}^{q_{2}} \equiv\left(\begin{array}{l}
1 \\
1 \\
0
\end{array}\right) \quad \int_{0}^{3} \equiv\left(\begin{array}{l}
1 \\
0 \\
1
\end{array}\right) \quad 0 \quad \equiv\left(\begin{array}{l}
0 \\
1 \\
1
\end{array}\right)
$$

Convex hall of characteristic vector $S=$ polytope


Computing a MST $=$ lincow optimisation over this poly tope

Question: How to optain a description of this polytope by linear constraints.
We solve this here for the MST probes.

Minimum Spanning Trees and Linear Programming (cont.)
Consider LP relaxation of the integer programming formulation:

$$
\begin{aligned}
& \min c^{T} \cdot x \\
& \text { s.t. } \quad x(\gamma(S)) \leq|S|-1 \\
& x(E)=|V|-1 \\
& x_{e} \geq 0
\end{aligned}
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\end{array}
$$

## Theorem 6.6.

Let $x^{*} \in\{0,1\}^{E}$ be the characteristic vector of an MST. Then $x^{*}$ is an optimal solution to the LP above.

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Let $x^{*} \in\{0,1\}^{E}$ be the characteristic vector of an MST. Then $x^{*}$ is an optimal solution to the LP above.

## Corollary 6.7.

The vertices of the polytope given by the set of feasible LP solutions are exactly the characteristic vectors of spanning trees of $G$. The polytope is thus the convex hull of the characteristic vectors of all spanning trees.
by definifion of cortex

Proof of Thm 6.6:
We compute a MST with Kruskal and show that its characteristic vector $x^{*}$ is an optimal solution of the LP.

Idea
Also construct a dual solution $p$ with Kruskal and show that the complementary slackness conditions are fulfilled.

Primal (P):

$$
\begin{array}{rlrl}
\left.\min \begin{array}{ll}
c^{T} \cdot x & \\
\text { s.t. } & x(\gamma(S))
\end{array}\right)|S|-1 \\
& x(E) & =|V|-1 \\
& x_{e} & \geq 0 & \forall \emptyset \neq S \subset V
\end{array} \quad \rightarrow \text { dual variables } z_{s}
$$

Dual (D):

$$
\begin{aligned}
\max & \sum_{\theta \pm S \subseteq v}(|s|-1) \cdot z_{s} \\
\text { sot. } \sum_{s: e \in \gamma(s)} z_{s} & \leqslant c_{c} \quad \forall e \\
z_{s} & \leqslant 0 \quad \forall \theta \neq S \nrightarrow V \\
z_{v} & \text { free }
\end{aligned}
$$

## Proof of Thm 6.6:

We compute a MST with Kruskal and show that its characteristic vector $x^{*}$ is an optimal solution of the LP.

## Idea

Also construct a dual solution $p$ with Kruskal and show that the complementary slackness conditions are fulfilled.

Primal (P):

$$
\begin{array}{rlrl}
\min & c^{T} \cdot x & \\
\text { s.t. } & x(\gamma(S)) & \leq|S|-1 & \forall \emptyset \neq S \subset V \\
& x(E) & =|V|-1 & \\
x_{e} & \geq 0 & \forall e \in E
\end{array}
$$

Dual (D):

$$
\begin{array}{cc}
\min & \\
& \sum_{\emptyset \neq S \subseteq V}(|S|-1) p_{S} \\
\text { s.t. } & \sum_{S: e \in \gamma(S)} p_{S} \geq-c(e) \\
& p_{S} \geq 0 \\
p_{V} \text { free } & \forall e \in E \\
& \forall \emptyset \neq S \subset V
\end{array}
$$

